| B.E ELECTRICAL AND ELECTRONICS ENGINEERING(EEE) CHOICE BASED CREDIT SYSTEM (CBCS) SEMESTER -VIII | | | | | | |
|--|--|---|---|------|--|--|
| INDUSTRIAL DRIVES AND APPLICATIONS(Core Course) | | | | | | |
| Subject Code | 15EE82 | IA Marks | 20 | | | |
| Number of Lecture Hours/Week | 04 | Exam Hours | 03 | | | |
| Total Number of Lecture Hours50Exam Marks8 | | | 80 | | | |
| Credits - 04 | | | | | | |
| Course objectives: To define electric drive, its parts, To explain dynamics and modes of To explain selection of motor power To analyze the performance of in | advantages and explain ch of operation of electric driv ver ratings and control of o duction motor drives unde | noice of electric drive. ves. dc motor using rectifiers. r different conditions. | | | | |
| • To explain the control of induction | n motor, synchronous mot | for and stepper motor dri | ves. | | | |
| • To discuss typical applications el | ectrical drives in the indus | try. ∎ | T. | 1. 2 | | |
| Module-1 | | | Ie He | | | |
| Electrical Drives: Electrical Drives, AChoice of Electrical Drives, Status of dDynamics of Electrical Drives: FunMultiquadrant Operation. EquivalentNature and Classification of LoadToOperations, SteadyState Stability, LoadControl Electrical Drives: Modes ofloop Control of Drives.Revised Bloom'sL1 – RememberinTaxonomy LevelModule-2 | Advantages of Electrical c and ac Drives. damental Torque Equation Values of DriveParameter orques, Calculation of Ti l Equalization. Operation, Speed Contro g, L_2 – Understanding, L_3 | Drives. Parts of Electrons, Speed TorqueConvers, Components of Loa me and Energy Loss i l and Drive Classificati – Applying, L ₄ – Analysi | entions and ad Torques, n Transient ons, Closed ng. | 0 | | |
| Module-2 | | | | | | |
| Selection of Motor Power Ratings: Thermal Model of Motor for Heating and Cooling, Classes of Motor Duty, Determination of Motor Rating. Direct Current Motor Drives: Controlled Rectifier Fed dc Drives, Single Phase Fully Controlled Rectifier Control of dc Separately Excited Motor, SinglePhase Half Controlled Rectifier Control of dc Separately Excited Motor, Three Phase Fully Controlled Rectifier Control of dc Separately Excited Motor Fed Form Fully Controlled Rectifier, Rectifier Control of dc Separately Excited Motor Fed Form Fully Controlled Rectifier, Control of dc Separately Excited Motor, Supply Harmonics, Power Factor and Ripple in Motor Current, Chopper Control of Separately Excited dcMotor, Chopper Control of Series Motor. ■ | | | | | | |
| Revised Bloom's L1 – Rememberin Taxonomy Level | g, L_2 – Understanding, L_3 | – Applying, L ₄ – Analys | ng. | | | |
| Module-3 | | | | | | |
| Induction Motor Drives: Analysis and with Unbalanced Source Voltage and S Impedances, Analysis of Induction Mot Braking, Transient Analysis.Speed Cor Frequency Control from Voltage SourceRevised Bloom'sL2 – Understanding | Performance of Three Pha bingle Phasing, Operation w or Fed From Non-Sinusoic ntrol Techniques-Stator Vo es. ■ Ig, L ₃ – Applying, L ₄ – An | use Induction Motors, Op with Unbalanced Rotor dal Voltage Supply,Starti oltage Control, Variable V alysing, L ₅ – Evaluating | eration 10 ng, Voltage | 0 | | |
| Taxonomy Level Module-4 | | | | | | |
| Induction Motor Drives (continued):Voltage Source Inverter (VSI) Control, CycloconverterControl, Closed Loop Speed Control and Converter Rating for VSI and Cycloconverter InductionMotor Drives, Variable Frequency Control from a Current Source, Current Source (CSI)Control,current regulated voltage source inverter control, speed control of single phase inductionmotors.Synchronous Motor Drives:Operation from fixed frequency supply-starting, synchronous motorRevised Bloom's Taxonomy LevelL1 – Remembering, L2 – Understanding, L3 – Applying, L4 – Analysing. | | | | | | |
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B.E ELECTRICAL AND ELECTRONICS ENGINEERING(EEE) CHOICE BASED CREDIT SYSTEM (CBCS) SEMESTER -VIII

| SEIVLESTER - VIII | | | | | | | |
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| 15EE82 INDUSTRIAL DRIVES AND APPLICATIONS(Core Course) (continued) | | | | | | | |
| Modu | ule-5 | | | | Teaching Hours | | |
| Syncl comm Moto Stepp Moto Indus | hronous Mote nutated thruste r Drives, Sinus oer Motor Da rs, Torque Ver strial Drives: | Dr Drives (continued): Self-contr r inverter, Starting Large Synchro soidal PMAC Motor Drives, Brus rives : Variable Reluctance, Perr rsus Stepping rate Characteristics, Fextile Mills, Steel Rolling Mills, | olled synchronous n pnous Machines, Per hless dc Motor Drive nanent Magnet, Imp Drive Circuits for S Cranes and Hoists, M | notor drive employing manent Magnet ac (Pl es. portant Features of St tepper Motor. Machine Tools. | g load 10 MAC) tepper | | |
| Revis Taxoi | ed Bloom's nomy Level | L_1 – Remembering, L_2 – Unders | standing, L ₃ – Applyi | ng, L ₄ – Analysing. | | | |
| Course outcomes: At the end of the course the student will be able to: Explain the advantages and choice of electric drive. Explain dynamics and different modes of operation of electric drives. Suggest a motor for a drive and control of dc motor using controlled rectifiers. Analyze the performance of induction motor drives under different conditions. Control induction motor, synchronous motor and stepper motor drives. Suggest a suitable electrical drive for specific application in the industry. ■ Graduate Attributes (As per NBA) Engineering Knowledge, Problem Analysis, Design/ Development of Solutions, Modern Tool Usage. | | | | | | | |
| Ques • • | stion paper p The question marks. There will be Each full que The students | pattern: paper will have ten full question e two full questions (with a maxin estion will have sub question cove will have to answer five full ques | ns carrying equal ma num of four sub ques ring all the topics un stions, selecting one f | rks. Each full questio tions) from each modu der a module. full question from each | n consisting of 16 1le. 1 module. | | |
| Техи | JUUK | | | | | | |
| 1 | Fundamental | s of Electrical Drives | Gopal K. Dubey | Narosa Publishing House | 2 nd Edition, 2001 | | |
| 2 | Electrical Dr (Refer to cha under module | ives: Concepts and Applications pter 07 for Industrial Drives e 5.) | VedumSubrahma nyam | McGraw Hill | 2 nd Edition, 2011 | | |
| Refe | rence Books | | | | | | |
| 1 | Electric Driv | es | N.K De,P.K. Sen | PHI Learning | 1 st Edition, 2009 | | |